

Parallel Multi-Resolution Fusion Network for Image Inpainting



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Introduction:

> Challenges:

- Most deep image inpainting methods are based on auto-encoder architecture, in which the spatial details of images will be lost in the down-sampling process, leading to the degradation of generated results.
- Texture information and structure information can not be well integrated into a serial conventional inpainting network like autoencoder.

> Our Contributions:

- This is the first work to introduce parallel multi-resolution network architecture into image inpainting, which is able to maintain high-resolution inpainting in the whole process and generate promising texture patterns for the inpainted images.
- Built on parallel multi-resolution network architecture, we propose novel mask-aware representation fusion and attention-guided representation fusion, which can fuse the low- and high-resolution representations more effectively.
- Extensive experiments validate that our method can produce more reasonable and fine-detailed results than other state-of-the-art methods.

Method:

Parallel Multi-Resolution Network

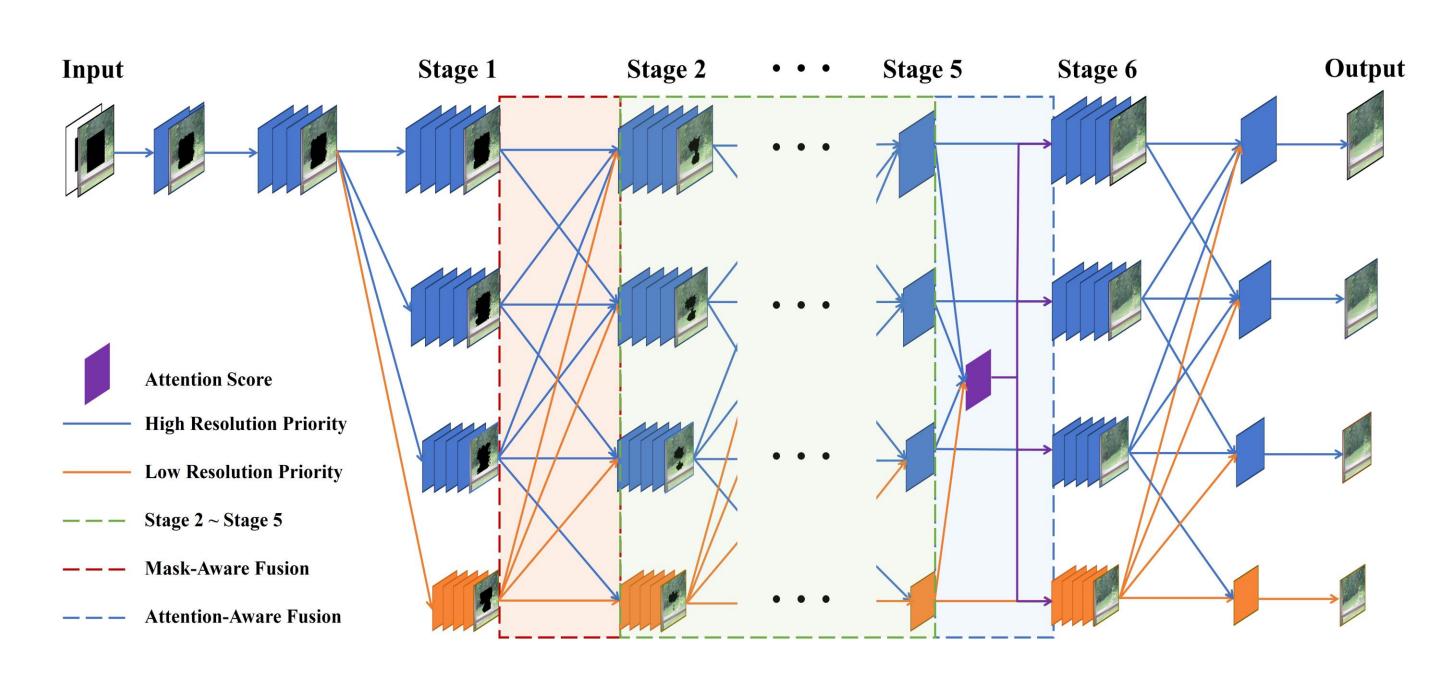


Figure 1. The architecture of Parallel Multi-Resolution Network.

Inpainting Priority

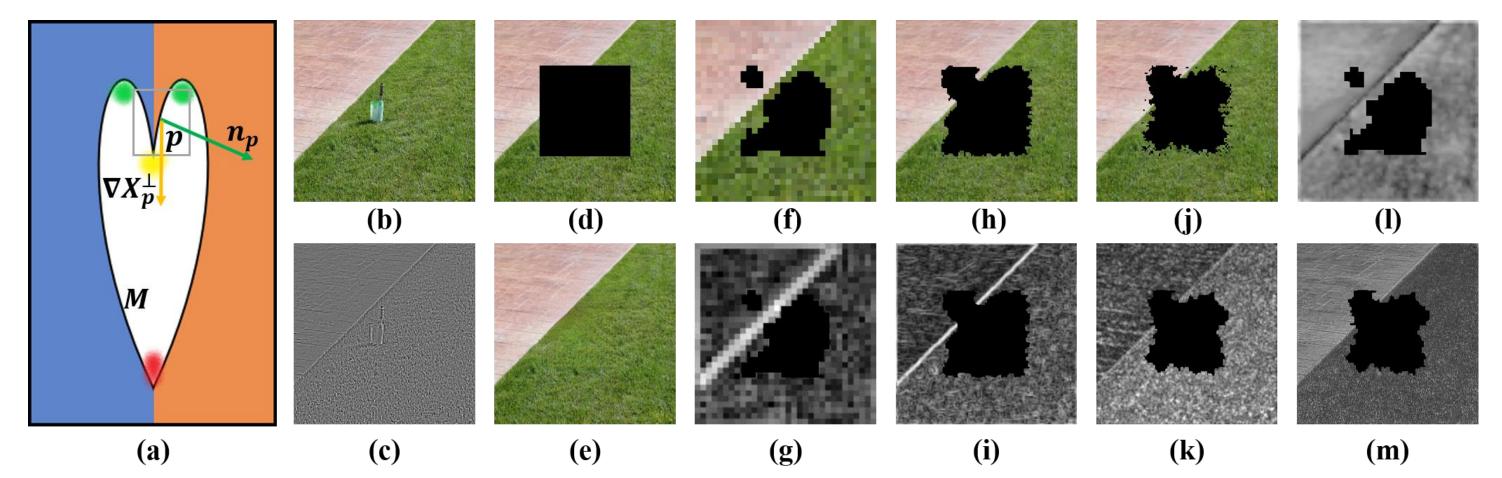


Figure 2. Illustration of common priority and resolution-specific priority.

The mask and feature update mechanism based on Inpainting Priority:

Step 1: Mask update

$$m' = \begin{cases} 1, & if \ m = 1 \ or \ q \ge \delta \cdot q^{max} \\ 0, & otherwise \end{cases}$$

The calculate of the pixel x priority q:

$$q = sum(\mathbf{M}_{p}) \cdot \rho^{l}(x)$$

Common priority term $sum(M_p)$: the more confidently the pixel can be inpainted with more valid surrounding pixels.

Low-resolution priority (l = 0):

$$\rho^l(x) = |n_p \cdot \nabla X_p^{\perp}|$$

High-resolution priority (l = 1,2,3):

$$\rho^{l}(x) = |n_{p} \cdot \nabla(X_{p} - X_{p\uparrow\downarrow})|$$

Step 2: Feature update

$$x_{p} = \begin{cases} \frac{\Omega_{p}}{sum(M_{p})} W \cdot (X_{p} \odot M_{p}) + b, & if m' = \\ 0, & otherwise \end{cases}$$

Experiments:

Quantitative Comparison on Places2

| | Mask | GC [39] | EC [25] | SF [28] | HF [37] | MEDFE [22] | Ours |
|------------------------------|--------|---------|---------|---------|---------|------------|--------|
| ℓ_1 (%) $^{\downarrow}$ | 0-10% | 1.74 | 1.18 | 2.71 | 2.41 | 1.30 | 1.12 |
| | 10-20% | 2.38 | 1.91 | 3.51 | 3.38 | 2.09 | 1.74 |
| | 20-30% | 3.36 | 2.91 | 4.55 | 4.67 | 2.66 | 2.60 |
| | 30-40% | 4.55 | 4.06 | 5.69 | 6.13 | 3.85 | 3.65 |
| | 40-50% | 5.96 | 5.42 | 7.00 | 7.93 | 5.31 | 4.89 |
| | 50-60% | 8.52 | 7.66 | 9.12 | 10.7 | 7.91 | 7.24 |
| | Ave% | 4.41 | 4.42 | 5.43 | 5.87 | 4.60 | 3.54 |
| \mathbf{SSIM}^{\uparrow} | 0-10% | 0.951 | 0.964 | 0.898 | 0.917 | 0.960 | 0.971 |
| | 10-20% | 0.913 | 0.921 | 0.855 | 0.859 | 0.925 | 0.934 |
| | 20-30% | 0.859 | 0.863 | 0.801 | 0.788 | 0.882 | 0.884 |
| | 30-40% | 0.799 | 0.802 | 0.745 | 0.714 | 0.819 | 0.827 |
| | 40-50% | 0.732 | 0.733 | 0.685 | 0.632 | 0.747 | 0.761 |
| | 50-60% | 0.640 | 0.646 | 0.610 | 0.536 | 0.649 | 0.669 |
| | Ave% | 0.816 | 0.806 | 0.765 | 0.741 | 0.805 | 0.840 |
| \mathbf{PSNR}^{\uparrow} | 0-10% | 31.085 | 32.441 | 28.609 | 28.825 | 31.707 | 33.690 |
| | 10-20% | 27.454 | 27.941 | 25.522 | 25.255 | 27.422 | 28.924 |
| | 20-30% | 24.466 | 24.931 | 23.121 | 22.635 | 25.855 | 25.871 |
| | 30-40% | 22.195 | 22.787 | 21.336 | 20.672 | 23.271 | 23.487 |
| | 40-50% | 20.395 | 21.043 | 19.818 | 18.903 | 21.211 | 21.659 |
| | 50-60% | 18.022 | 18.957 | 17.981 | 16.841 | 18.738 | 19.220 |
| | Ave% | 23.937 | 25.700 | 22.732 | 22.188 | 25.220 | 25.475 |
| FID↓ | 0-10% | 1.40 | 1.60 | 3.74 | 1.95 | 1.46 | 1.25 |
| | 10-20% | 2.60 | 3.18 | 5.00 | 5.20 | 3.27 | 2.30 |
| | 20-30% | 4.18 | 5.87 | 6.92 | 11.54 | 7.23 | 4.14 |
| | 30-40% | 7.20 | 9.90 | 9.47 | 22.36 | 14.34 | 6.57 |
| | 40-50% | 11.70 | 15.65 | 13.07 | 39.98 | 25.78 | 10.61 |
| | 50-60% | 19.88 | 25.55 | 21.70 | 70.91 | 43.90 | 16.99 |
| | Ave% | 7.71 | 13.58 | 9.98 | 25.32 | 22.68 | 6.98 |

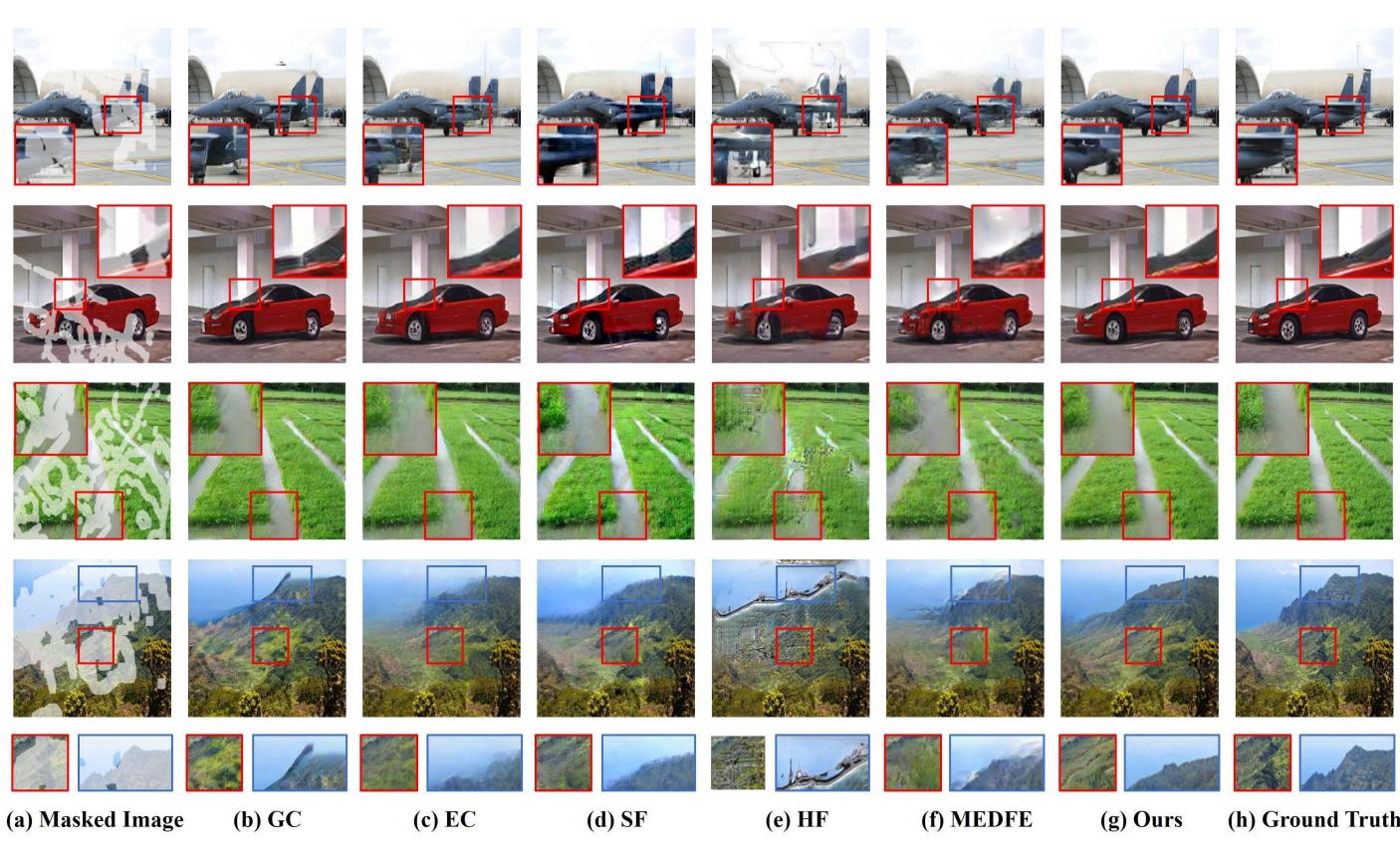


Figure 3. The qualitative comparison on Places2.